

Data sheet for three-phase Squirrel-Cage-Motors INNOMOTICS



Motor type : 1AV2094D

INNOMOTICS GP - 90 L - IM B3 - 8p

Client order no.	Item-No.	Offer no.
Order no.	Consignment no.	Project

Remarks

Electrical data **Safe Area**

U [V]	Δ/Y	f [Hz]	P [kW]	P [hp]	I [A]	n [1/min]	M [Nm]	$\eta^{(3)}$			$\cos\phi^{(3)}$			I_A/I_N	M_A/M_N	M_R/M_N	M_B/M_N	IE-CL
								4/4	3/4	2/4	4/4	3/4	2/4	I_V/I_N	T_I/T_N	T_B/T_N		
DOL duty (S1) - 155(F) to 130(B)																		
400	Δ	50	0.55	-/-	1.74	665	7.9	61.7	63.4	59.8	0.74	0.63	0.49	2.7	1.5	1.7		IE2
690	Y	50	0.55	-/-	1.01	665	7.9	61.7	63.4	59.8	0.74	0.63	0.49	2.7	1.5	1.7		IE2
460	Δ	60	0.63	-/-	1.77	820	7.3	62.0	62.9	59.5	0.72	0.62	0.48	2.9	1.5	1.8		IE2
460	Δ	60	0.55	-/-	1.69	840	6.3	62.0	61.2	56.5	0.66	0.56	0.43	3.1	1.8	2.1		IE2

IM B3 / IM 1001	FS 90 L	IP55	UKCA	IEC/EN 60034	IEC, DIN, ISO, VDE, EN
Environmental conditions : -20 °C - +40 °C / 1000 m			Locked rotor time (hot / cold) : 41.70 s 72.00 s		

Mechanical data

Sound level (SPL / SWL) at 50Hz 60Hz	53.0 / 65.0 dB(A) <small>2) 3)</small>	57.0 / 69.0 dB(A) <small>2) 3)</small>	Vibration severity grade	A
Moment of inertia	0.0026 kg m ²		Thermal class	F
Bearing DE NDE	6205 2Z C3	6004 2Z C3	Duty type	S1
Bearing lifetime L _{10mh} F _{Rad min} for coupling operation 50 60Hz ¹⁾	40000 h	32000 h	Direction of rotation	bidirectional
Regreasing device	Without		Frame material	aluminum
Grease nipple	Without		Net weight of the motor (IM B3)	kg
Type of bearing	Preloaded bearing DE		Coating (paint finish)	Standard paint finish C2
Condensate drainage holes	Without		Color, paint shade	RAL7030
External earthing terminal	Without		Motor protection	(A) without (Standard)
			Method of cooling	IC411 - self ventilated, surface cooled
			Carbon footprint (without options)	58kg

Terminal box

Terminal box position	top	Max. cross-sectional area	4.0 mm ²
Material of terminal box	Aluminium	Main cable entry	1xM25x1.5
Type of terminal box	TB1 E00	Main cable gland	1 plug
Contact screw thread	3xM4		

I_A/I_N = locked rotor current / current nominal
 M_R/M_N = locked rotor torque / torque nominal
 M_B/M_N = break down torque / nominal torque
¹⁾ L_{10mh} according to DIN ISO 28110/2010
²⁾ at rated power / at full load
³⁾ Value is valid only for DOL operation with motor design IC411

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Responsible department IN LV	Technical reference	Created by IPC	Approved by	Technical data are subject to change! There may be discrepancies between calculated and rating plate values.	
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